

UNITS: INCHES

FRAME SIZE	MOTOR DIMENSIONS										CONDUIT BOX									
	A	B	C	D	G	J	K	M	O	P	T	AA	AB	AC	AE	AF	XL	XN		
404TS	19.7	15.0	29.6	10.00	1.1	4.0	4.2	12.6	20.3	20.3	2.8	3.00	20.2	15.1	13.0	8.7	15.7	11.5		
404T	19.7	15.0	32.6	10.00	1.1	4.0	4.2	12.6	20.3	20.3	2.8	3.00	20.2	15.1	13.0	8.7	15.7	11.5		
FRAME SIZE	MOUNTING										SHAFT EXTENSION			KEY SEAT			BEARINGS			MAXIMUM WEIGHT
404T	E	2F	H	BA	HA	N-W	V	U	R	S	ES	LS	OS							
404T	8.00	12.25	0.81	6.62	4.25	4.00	2.125	1.845	0.500	2.75	6.313C3	6.313C3	6.313C3	1050	lbs.					
404T	8.00	12.25	0.81	6.62	7.25	7.00	2.875	2.450	0.750	5.62	6.317C3	6.317C3	6.313C3	1050	lbs.					

CUSTOMER: _____ MOTOR MODEL NO.: _____ TAG NO's: _____

P.O. NO.: _____ HP: _____ VOLTAGE: _____ RPM(SYN.): _____ HZ: _____
 FRAME SIZE: _____ PRODUCT TYPE: ODP EQP III, EPACT, & HIGH EFFICIENCY
 COMMENTS: _____

 PER: _____ DATE: _____

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 DO NOT USE FOR CONSTRUCTION, INSTALLATION, OR APPLICATION PURPOSES UNLESS THE DRAWING IS MARKED AS CERTIFIED CERTIFIED

- NOTES:
1. DIMENSION V REPRESENTS LENGTH OF STRAIGHT PART OF SHAFT OF STRAIGHT PART OF SHAFT
 2. MAIN CONDUIT BOX MAY BE ROTATED IN 90° INCREMENTS
 3. KEY DIMENSIONS EQUAL S x S x 5.62 FOR T AND S x S x 2.75 FOR TS (MOTOR SUPPLIED WITH KEY)
 4. MOTOR WEIGHT SHOWN IS MAXIMUM HORSEPOWER IN FRAME
 5. OPPOSITE ROTATION AVAILABLE ONLY BY CONNECTION CHANGE

STANDARD (NO AUX. BOXES)
 RTD AUX. BOX
 SPACE HEATER AUX. BOX
 BEARING RTD's

TOSHIBA
 TOSHIBA INTERNATIONAL CORPORATION
 OPEN DRIP-PROOF
 HORIZONTAL FOOT-MOUNTED
 3 PHASE INDUCTION MOTOR
 F1 ASSEMBLY

XT SERIES
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TYPICAL MOTOR PERFORMANCE DATA

Model: B1004VLF3USH

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
100	75	4	1777	404T	575	60	3	91
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
ODP	12	F	1.15	CONT	95.4	B	G	40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	100	74.6	90.2	95.3	87.1
¾ Load	75.00	55.9	69.4	95.6	86.0
½ Load	50.00	37.3	50.3	95.6	81.0
¼ Load	25.00	18.6	34.5	90.5	59.9
No Load			21.2		6.2
Locked Rotor			580.00		41.9

Torque				Rotor wk ²
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	Inertia (lb-ft ²)
296	220	155	255	29.62

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
18	8	-	6317C3	6313C3	

*Bearings are the only recommended spare part(s).

Motor Options:
Product Family:EQPIII ODP
Mounting:Footed,Shaft:T Shaft

Customer	
Customer PO	
Sales Order	
Project #	

Tag:

All characteristics are average expected values.

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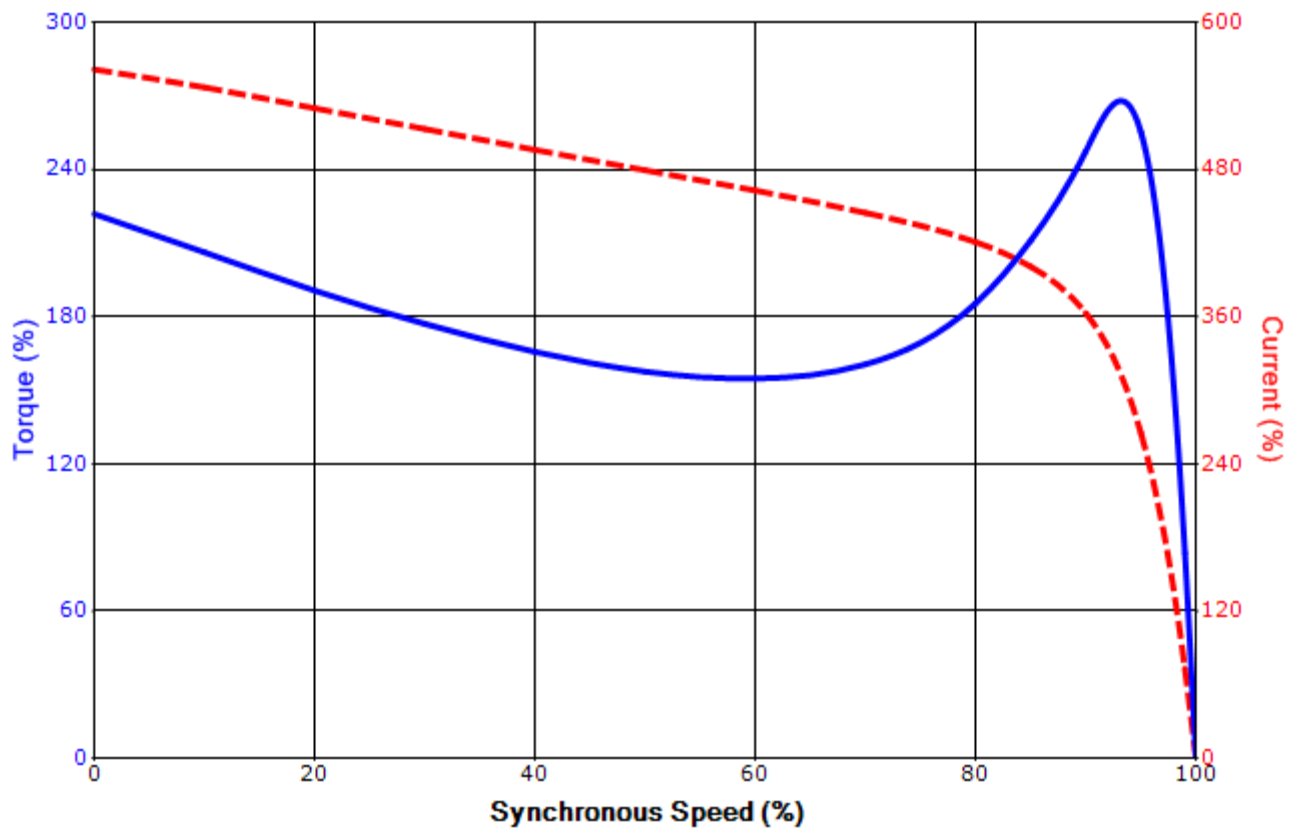
Engineering	aacosta	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	5/22/2012	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

SPEED TORQUE/CURRENT CURVE

Model: B1004VLF3USH

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
100	75	4	1777	404T	575	60	3	91
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
ODP	12	F	1.15	CONT	95.4	B	G	40 C
Locked Rotor Amps	Rotor wk ² Inertia (lb-ft ²)	Torque						Break Down (%)
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)				
580.00	29.62	296	220	155			255	

Design Values



Customer		wk ² Load Inertia (lb-ft ²)	-
Customer PO		Load Type	-
Sales Order		Voltage (%)	100
Project #		Accel. Time	-

Tag:

All characteristics are average expected values.

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Engineering	aacosta	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1121 / 0
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Motor Connection Diagrams
12 Leads

Across-the-Line Starting / Running Connections

Low Voltage Delta



High Voltage Delta



Switch L1 and L2 to reverse rotation

Suitable for Wye-Delta Starting and Limited Part-Winding-Starting.
Please Contact Toshiba International for specific connections.