

PWL440-10-JOG

**1Q PWM NEMA 4X Adjustable Speed Drive
with JOG switch**

for PMDC or Field Wound Brushed Motors

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Full manual available online

Specifications

Model	Line Voltage (VAC)	Armature Voltage Range (VDC)	Continuous Armature Current (Amps)	Horsepower Range
PWL440-10-JOG	115	0 - 130	10.0	1/4 - 1
	230	0 - 240		1/2 - 2

AC Line Voltage.....115/230 VAC $\pm$ 10%, 50/60 Hz, single phase

Form Factor.....1.05

Field Voltage with 115 VAC line voltage.....50 or 100 VDC

with 230 VAC line voltage.....100 or 200 VDC

Maximum Field Current.....1 Amp

Acceleration Time Range with 130 VDC armature voltage.....1 - 10 seconds

with 240 VDC armature voltage.....1 - 15 seconds

Deceleration Time Range with 130 VDC armature voltage.....coast to stop - 10 seconds

with 240 VDC armature voltage.....coast to stop - 19 seconds

Analog Input Voltage Range (Signal must be isolated; S1 to S2)

with 115 VAC line voltage.....0 - 2.5 VDC

with 230 VAC line voltage.....0 - 5 VDC

Input Impedance (S1 to S2).....50K ohms

Load Regulation.....1% base speed or better

Speed Range.....100:1

Vibration (0 - 50 Hz).....0.5G maximum

(>50 Hz).....0.1G maximum

Ambient Temperature Range.....10°C - 40°C

Weight.....7.2 lbs

Safety Certifications.....UL/cUL Recognized Equipment, file # E132235

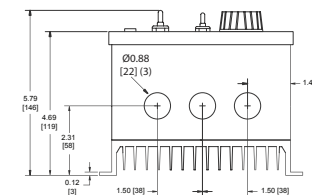
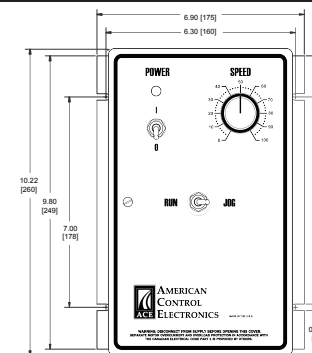
.....CSA Certified Component, file # LR41380

Safety Warnings

READ ALL SAFETY WARNINGS BEFORE INSTALLING THIS EQUIPMENT

- **DO NOT INSTALL, REMOVE, OR REWIRE THIS EQUIPMENT WITH POWER APPLIED.** Have a qualified electrical technician install, adjust and service this equipment. Follow the National Electrical Code and all other applicable electrical and safety codes, including the provisions of the Occupational Safety and Health Act (OSHA), when installing equipment.
- **Circuit potentials are at 115 or 230 VAC above earth ground.** Avoid direct contact with the printed circuit board or with circuit elements to prevent the risk of serious injury or fatality. Use a non-metallic screwdriver for adjusting the calibration trim pots. Use approved personal protection equipment and insulated tools if working on this drive with power applied.
- Reduce the chance of an electrical fire, shock, or explosion by using proper grounding techniques, over-current protection, thermal protection, and enclosure. Follow sound maintenance procedures.
- **ACE strongly recommends the installation of a master power switch in the line voltage input.** The switch contacts should be rated for 250 VAC and 200% of motor nameplate current.
- **Removing AC line power is the only acceptable method for emergency stopping.** Do not use dynamic braking, decelerating to minimum speed, or coasting to a stop for emergency stopping. They may not stop a drive that is malfunctioning. Removing AC line power is the only acceptable method for emergency stopping.
- Line starting and stopping (applying and removing AC line voltage) is recommended for infrequent starting and stopping of a drive only. Dynamic braking, decelerating to minimum speed, or coasting to a stop is recommended for frequent starts and stops. Frequent starting and stopping can produce high torque. This may cause damage to motors.
- **Do not disconnect any of the motor leads from the drive** unless power is removed or the drive is disabled. Opening any one lead while the drive is running may destroy the drive.
- The field output is for shunt wound motors only. Do not make any connections to F1 and F2 when using a permanent magnet motor.
- Change voltage switch settings only when the drive is disconnected from AC line voltage. Make sure both switches are set to their correct position. If the switches are improperly set to a lower voltage position, the motor will not run at full voltage and may cause damage to the transformer. If the switches are improperly set to a higher voltage, the motor will overspeed, which may cause motor damage, or result in bodily injury or loss of life.
- Under no circumstances should power and logic level wires be bundled together.
- Be sure potentiometer tabs do not make contact with the potentiometer's body. Grounding the input will cause damage to the drive.
- This product does not have internal solid state motor overload protection. It does not contain speed-sensitive overload protection, thermal memory retention, or provisions to receive and act upon signals from remote devices for over temperature protection. If motor protection is needed in the end-use product, it needs to be provided by additional equipment in accordance with NEC standards.

Dimensions



ALL DIMENSIONS IN INCHES [MILLIMETERS]

Installation

Mounting

NEMA 4X cased drives come with two 0.88 inch (22 mm) conduit knockout holes at the bottom of the case. The drives may be vertically wall mounted using the four 0.19 inch (5 mm) slotted holes on the attached heat sink. For loads less than 5 amps, the drive may be bench mounted horizontally or operated without mounting.

1. Install the mounting screws.
2. For access to the terminal strip, turn the slotted screw on the front cover counterclockwise until it is free from the case. The right side of the cover is hinged to the case. Pull the slotted screw to open the case.
3. Carefully remove the conduit knockouts by tapping them into the case and twisting them off with pliers.
4. Set the POWER switch to the OFF position before applying AC line voltage.
5. Install conduit hardware through the 0.88 inch (22 mm) knockout holes. Connect external wiring to the terminal block.
6. Grasp the slotted screw and tilt the front cover back into place. Avoid pinching any wires between the front cover and the case.
7. Turn the slotted screw clockwise until tight to secure the front cover.

Wiring

Use 14 - 16 AWG wire for AC line and motor wiring.

Shielding Guidelines

As a general rule, it is recommended to shield all conductors. If it is not practical to shield power conductors, it is recommended to shield all logic-level leads. If shielding of logic-level leads is not practical, the user should twist all logic leads with themselves to minimize induced noise. It may be necessary to earth ground the shielded cable. If noise is produced by devices other than the drive, ground the shield at the drive end. If noise is generated by the drive, ground the shield at the end away from the drive. Do not ground both ends of the shield.

Fusing

PWL440-10 series drives provide on board fusing for the AC line (L1, 230). Fuses are fast acting fuses rated for 15A at 250 VAC.

Connections

POWER

Line Input

Connect the AC line power leads to terminals L1 and 115 if using 115 VAC line power or to terminals L1 and 230 if using 230 VAC line power.

Motor

Connect the DC armature leads to terminals A1 and A2. If the motor does not spin in the desired direction, power down the drive and reverse these connections.

Field

At 115 VAC, connect the field leads to terminals F+ and L1 for a 50 VDC field or to F+ and F- for a 100 VDC field. At 230 VAC, connect the field leads to terminals F+ and L1 for a 100 VDC field or to F+ and F- for a 200 VDC field.

Do not make any connections to F+ and F- if using a permanent magnet motor.

LOGIC

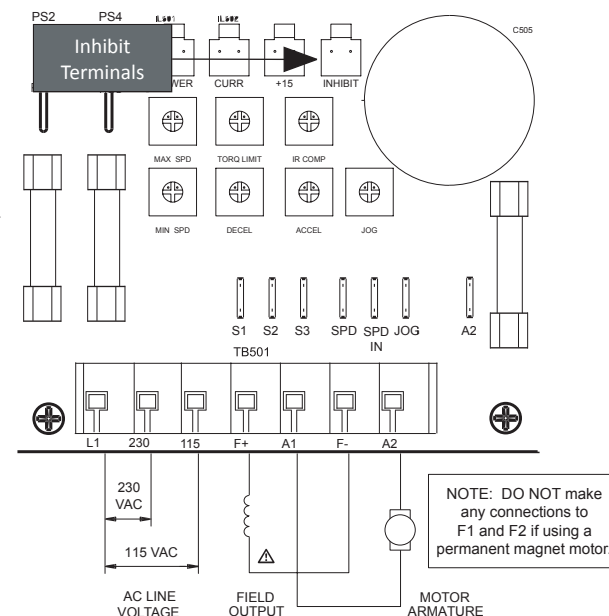
Speed Potentiometer (Pre-wired)

PWL440 series drives are pre-installed with a 10K ohm, 1/4 W potentiometer for speed control.

Inhibit

Short the INHIBIT terminals to coast the motor to zero speed. Open the INHIBIT terminals to accelerate the motor to set speed. Twist inhibit wires and separate them from power-carrying wires or sources of electrical noise. Use shielded cable if the inhibit wires are longer than 18 inches (46 cm). If shielded cable is used, ground only one end of the shield to earth ground. Do not ground both ends of the shield. **Do not use the inhibit for emergency stopping.**

ACE offers two accessory plug harnesses for connecting to the inhibit terminals; part number KTW-0001 [18 in (46 cm) leads] and part number KTW-0002 [36 in (91 cm) leads].



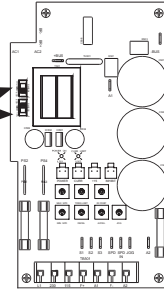
Startup

SELECT SWITCHES

Input Voltage Select (SW501, SW502)

Set the voltage switch SW501 and SW502 to either 115V or 230V to match the AC line voltage.

Input Voltage Select
(SW501, SW502)



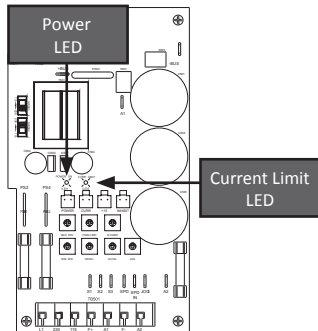
STARTUP

- Verify that no foreign conductive material is present on the printed circuit board.
- Ensure that all switches are properly set.

1. Turn the speed adjust potentiometer to "0" (full CCW).
2. Set the POWER switch to the ON position.
3. Slowly advance the speed adjust potentiometer clockwise (CW). The motor slowly accelerates as the potentiometer is turned CW. Continue until the desired speed is reached.
4. Set the POWER switch to the OFF position to coast the motor to a stop.

LEDs

Current Limit (CURR LIMIT): Red LED lights whenever the drive reaches current limit.
Power (POWER ON): Green LED lights whenever AC line voltage is applied to the drive.



MODES

Run Mode

Set the switch on the front cover to RUN to drive the motor at a speed determined by the speed adjust potentiometer on the front cover.

Jog Mode

Set the switch on the front cover to JOG to drive the motor at a speed determined by the JOG trim pot.

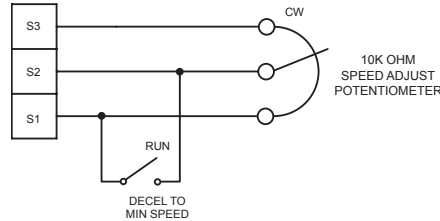
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Operation

DECELERATING & STOPPING

Decelerate to Minimum Speed

The switch shown below may be used to decelerate a motor to a minimum speed. Closing the switch between S1 and S2 decelerates the motor from set speed to a minimum speed determined by the MIN SPD trim pot setting. If the MIN SPD trim pot is set full CCW, the motor decelerates to zero speed when the switch between S1 and S2 is closed. The DECEL trim pot setting determines the rate at which the drive decelerates. By opening the switch, the motor accelerates to set speed at a rate determined by the ACCEL trim pot setting.

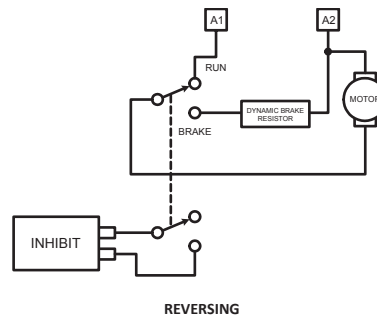


Decelerate to Zero Speed (Coast)

See INHIBIT in the CONNECTIONS section on page 1 for a description of wiring and connection locations.

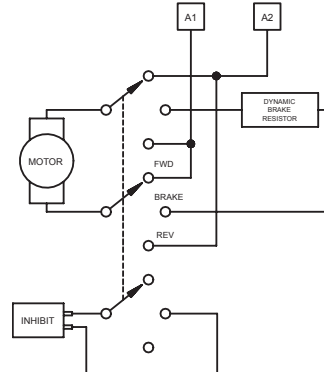
Decelerate to Zero Speed (Dynamic Brake)

Dynamic braking may be used to rapidly stop a motor. For the RUN/BRAKE switch, use a two pole, two position switch rated for at least the armature voltage rating and 150% of the armature current rating. For the dynamic brake resistor, use a 40 watt minimum, high power, wirewound resistor. Sizing the dynamic brake resistor depends on load inertia, motor voltage, and braking time. Use a lower-value, higher-wattage dynamic brake resistor to stop a motor more rapidly. Recommended values are 15 ohms for a 130 VDC motor and 30 ohms for 240 VDC motor.



Reversing with a Dynamic Brake

A dynamic brake may be used when reversing the motor direction. Use a three pole, three position switch rated for at least the armature voltage rating and 150% of the armature current rating. For the dynamic brake resistor, use a 40 watt minimum, high power, wirewound resistor. Sizing the dynamic brake resistor depends on load inertia, motor voltage, and braking time. Use a lower-value, higher-wattage dynamic brake resistor to stop a motor more rapidly. Recommended values are 15 ohms for a 130 VDC motor and 30 ohms for 240 VDC motor. **The motor must come to a complete stop before changing directions.**



Calibration

Minimum Speed (MIN SPD): The MIN SPD setting determines the minimum motor speed when the speed adjust potentiometer is set for minimum speed. It is factory set for zero speed. To calibrate the MIN SPD:

1. Set the MIN SPD trim pot full CCW.
2. Set the speed adjust potentiometer for minimum speed.
3. Adjust the MIN SPD trim pot until the desired minimum speed is reached or is just at the threshold of rotation.

Maximum Speed (MAX SPD): The MAX SPD setting determines the maximum motor speed when the speed adjust potentiometer is set for maximum speed. To calibrate the MAX SPD:

1. Set the MAX SPD trim pot full CCW.
2. Set the speed adjust potentiometer for maximum speed.
3. Adjust the MAX SPD trim pot until the desired maximum speed is reached.

Check the MIN SPD and MAX SPD adjustments after recalibrating to verify that the motor runs at the desired minimum and maximum speed.

Torque (TORQ LIMIT): The TORQ LIMIT setting determines the maximum torque for accelerating and driving the motor. To calibrate the TORQ LIMIT:

1. With the power disconnected from the drive, connect a DC ammeter in series with the armature.
2. Set the TORQ LIMIT trim pot to minimum (full CCW).
3. Set the speed adjust potentiometer to maximum speed (full CW).
4. Carefully lock the motor armature. Be sure that the motor is firmly mounted.
5. Apply line power. The motor should be stopped.
6. Slowly adjust the TORQ LIMIT trim pot CW until the armature current is 150% of motor rated armature current. **Continuous operation beyond this rating may damage the motor.**
7. Turn the speed adjust potentiometer CCW.
8. Remove line power.
9. Remove the stall from the motor.
10. Remove the ammeter in series with the motor armature if it is no longer needed.

IR Compensation (IR COMP): The IR COMP setting determines the degree to which motor speed is held constant as the motor load changes. To calibrate the IR COMP:

1. Set the IR COMP trim pot full CCW.
2. Increase the speed adjust potentiometer until the motor runs at midspeed without load. A handheld tachometer may be used to measure motor speed.
3. Load the motor armature to its full load armature current rating. The motor should slow down.
4. While keeping the load on the motor, rotate the IR COMP trim pot until the motor runs at the speed measured in step 2. If the motor oscillates (overcompensation), the IR COMP trim pot may be set too high (CW). Turn the IR COMP trim pot CCW to stabilize the motor.
5. Unload the motor.

Acceleration (ACCEL): The ACCEL setting determines the time the motor takes to ramp to a higher speed. ACCEL is factory set for the shortest acceleration time (full CCW). To calibrate the ACCEL:

1. Set the speed adjust potentiometer for minimum speed.
2. Set the speed adjust potentiometer for maximum speed. Measure the time it takes the motor to go from minimum speed to maximum speed.
3. If the time measured in step 2 is not the desired acceleration time, turn the ACCEL trim pot CW for a longer acceleration time, or CCW for a shorter acceleration time. Repeat steps 1 through 3 until the acceleration time is correct.

Deceleration (DECEL): The DECEL setting determines the time the motor takes to ramp to a lower speed. DECEL is factory set for the shortest deceleration time (full CCW). To calibrate the DECEL:

1. Set the speed adjust potentiometer for maximum speed.
2. Set the speed adjust potentiometer for minimum speed. Measure the time it takes the motor to go from maximum speed to minimum speed.
3. If the time measured in step 2 is not the desired deceleration time, turn the DECEL trim pot CW for a longer deceleration time, or CCW for a shorter deceleration time. Repeat steps 1 through 3 until the deceleration time is correct.

Jog (JOG): The JOG setting determines the constant motor speed when the drive is set to Jog mode. To calibrate the JOG:

1. Make sure the drive is in Jog mode. This is done by connecting the SPD IN and JOG terminals.
2. Turn the JOG trim pot until the motor runs at the desired JOG speed.